

ΦΥΣΙΚΗ ΠΡΟΣΑΝΑΤΟΛΙΣΜΟΥ
(Ενδεικτικές απαντήσεις)

ΘΕΜΑ Α

$$A_1 \rightarrow \delta, A_2 \rightarrow \beta, A_3 \rightarrow \alpha, A_4 \rightarrow \gamma, A_5 \rightarrow \alpha \rightarrow \Sigma, \beta \rightarrow \Sigma, \gamma \rightarrow \Lambda, \delta \rightarrow \Lambda, \epsilon \rightarrow \Sigma$$

ΘΕΜΑ Β

$$B_1 \rightarrow (iii)$$

$$\text{για περίοδο } T_1 \rightarrow \text{είναι δυο δεσμοί άρα } N_1 + 1 = 2 \Rightarrow N_1 = 1 \quad \text{άρα} \quad L = \frac{\lambda_1}{4} + 1 \cdot \frac{\lambda_1}{2} \Rightarrow L = \frac{3\lambda_1}{4} \quad (1)$$

$$\text{για περίοδο } T_2 \rightarrow \text{είναι 3 δεσμοί άρα } N_2 + 1 = 3 \Rightarrow N_2 = 2 \quad \text{άρα} \quad L = \frac{\lambda_2}{4} + 2 \cdot \frac{\lambda_2}{2} \Rightarrow L = \frac{5\lambda_2}{4} \quad (2)$$

$$\text{από (1) και (2)} \Rightarrow 3 \frac{\lambda_1}{4} = 5 \frac{\lambda_2}{4} \Rightarrow 3 \cdot v \cdot T_1 = 5 \cdot v \cdot T_2 \Rightarrow \boxed{\frac{T_1}{T_2} = \frac{5}{3}}$$

$$B_2 \rightarrow (i)$$

όταν η απόσταση μεταξύ τους είναι r :

$$F_1 = \frac{\mu_0}{4\pi} \cdot \frac{2I_1}{r} \cdot I_2 \cdot \ell = \frac{\mu_0}{4\pi} \cdot \frac{2I}{r} \cdot 2I \cdot \ell \quad (1)$$

όταν η απόσταση μεταξύ τους γίνει $\frac{3r}{2}$:

$$F_2 = \frac{\mu_0}{4\pi} \cdot \frac{2I_1}{\frac{3r}{2}} \cdot I'_2 \cdot \ell = \frac{\mu_0}{4\pi} \cdot \frac{2I}{\frac{3r}{2}} \cdot 4I \cdot \ell \quad (2)$$

$$\text{από } \frac{(1)}{(2)} \Rightarrow \frac{F_1}{F_2} = \frac{1}{4} \Rightarrow \boxed{\frac{F_1}{F_2} = \frac{3}{4}}$$

$$ZB_3 \rightarrow ii$$

Το σύστημα ισορροπεί:

$$\begin{aligned} \sum \vec{\tau}_{(O)} = 0 &\Rightarrow W_{1y} \cdot \ell_1 + W_y \cdot \frac{\ell_1}{2} - W_y \cdot \frac{\ell_2}{2} = 0 \\ &\Rightarrow \frac{m}{2} \cdot g \cdot \eta\mu\phi \cdot \ell_1 + m \cdot g \cdot \eta\mu\phi \cdot \frac{\ell_1}{2} = m \cdot g \cdot \eta\mu\phi \cdot \frac{\ell_2}{2} \Rightarrow \\ &\Rightarrow \ell_1 + \ell_1 = \ell_2 \Rightarrow 2\ell_1 = \ell_2 \Rightarrow \boxed{\frac{\ell_1}{\ell_2} = \frac{1}{2}} \end{aligned}$$

ΘΕΜΑ Γ

$$\Gamma 1. \lambda = 8\lambda_c$$

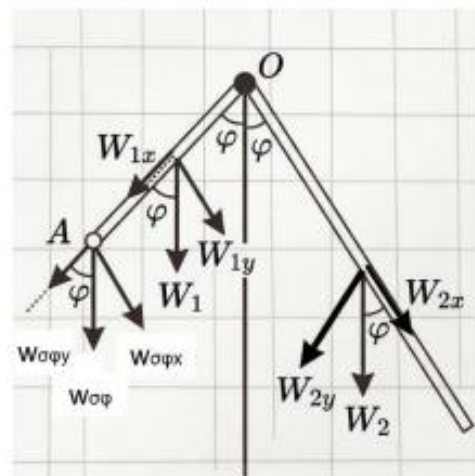
$$\lambda' - \lambda = \frac{h}{m_e c} (1 - \cos\varphi) \Rightarrow \lambda' = 8\lambda_c + \lambda_c \cdot 2 \Rightarrow \boxed{\lambda' = 10\lambda_c}$$

$$\Gamma 2.$$

$$\bullet \quad E_\varphi = h \cdot \frac{c}{\lambda} \Rightarrow E_\varphi = h \cdot \frac{c}{8\lambda_c} \Rightarrow E_\varphi = \frac{h \cdot c}{8 \cdot \frac{h}{m_e c}} \Rightarrow \boxed{E_\varphi = \frac{m_e c^2}{8}}$$

$$I = I_1 \uparrow \quad \left| \begin{array}{c} \leftarrow \bullet \\ - r - \end{array} \right| \quad \begin{array}{c} F_1 \\ \uparrow I_2 = 2I \end{array}$$

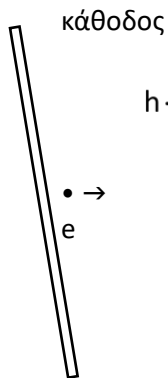
$$I = I_1 \uparrow \quad \left| \begin{array}{c} \leftarrow \bullet \\ - r + \frac{r}{2} - \end{array} \right| \quad \begin{array}{c} F_2 \\ \uparrow I'_2 = 4I \end{array}$$



ΦΡΟΝΤΙΣΤΗΡΙΟ ΠΡΟΥΠΥΛΑΙΑ ΡΕΘΥΜΝΟ

- $E_{\varphi'} = h \cdot \frac{c}{\lambda'} \Rightarrow E_{\varphi'} = h \cdot \frac{c}{10\lambda_c} \Rightarrow E_{\varphi'} = h \cdot \frac{c}{10 \cdot \frac{h}{m_e c}} \Rightarrow E_{\varphi'} = \frac{m_e c^2}{10}$
- $E_{\varphi} = E_{\varphi'} + K_e \Rightarrow K_e = \frac{m_e c^2}{8} - \frac{m_e c^2}{10} \Rightarrow K_e = \frac{2m_e c^2}{80} \Rightarrow K_e = \frac{m_e c^2}{40} = \frac{5 \cdot 10^5 \text{ eV}}{40} \Rightarrow K_e = 1,25 \cdot 10^4 \text{ eV}$

Γ3.



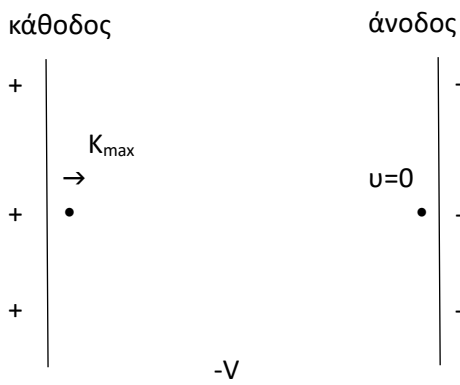
Από εξίσωση Einstein: $E_{\phi} = K_{\max} + \Phi \Rightarrow$

αν $K_{\max} = 0$ τότε $E_{\phi} = \Phi \Rightarrow$

$$h \cdot f_0 = \Phi \Rightarrow f_0 = \frac{\Phi}{h} \Rightarrow f_0 = \frac{1,4 \cdot 1,6 \cdot 10^{-19} \text{ J}}{6,4 \cdot 10^{-34} \text{ J} \cdot \text{s}} \Rightarrow$$

$$\Rightarrow f_0 = \frac{1,4}{4} \cdot 10^{15} \Rightarrow f_0 = \frac{7}{2} \cdot 10^{14} \text{ Hz}$$

Γ4.



ΘΜΚΕ από κάθοδο $\rightarrow$ άνοδο

$$W_{\text{ολ}} = \Delta K \Rightarrow -V_0 \cdot |e| = 0 - K_{\max} \Rightarrow$$

$$V_0 = \frac{K_{\max}}{|e|} \Rightarrow V_0 = \frac{h \cdot \frac{c}{\lambda_1} - \Phi}{e} \Rightarrow$$

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$$\Rightarrow V_0 = \frac{1200 \cdot \cancel{1,6 \cdot 10^{-19}} \cdot 10^{-9}}{400 \cdot 10^{-9}} - 1,4 \cdot \cancel{1,6 \cdot 10^{-19}} \Rightarrow V_0 = \frac{3-1,4}{1} \Rightarrow \boxed{V_0 = 1,6 \text{ Volt}}$$

ΘΕΜΑ Δ

Δ1.

- Ο ΚΛ ισορροπεί: $\sum \vec{F}_y = 0 \Rightarrow F - T - W_2 = 0 \Rightarrow$

$$T = F - W_2 \Rightarrow T = 3 - 1 \Rightarrow \boxed{T = 2 \text{ N}}$$

- το Σ στη θέση που ισορροπεί με το νήμα:

$$\sum \vec{F}_y = 0 \Rightarrow T' - F_{\epsilon\lambda} - W_1 = 0 \Rightarrow F_{\epsilon\lambda} = T' - W_1 \Rightarrow$$

$$\Rightarrow K \cdot \Delta\ell = T' - m_1 \cdot g \Rightarrow \Delta\ell = \frac{2-1}{10} \Rightarrow \boxed{\Delta\ell = 0,1 \text{ m}}$$

- Το Σ στη Θ1 της ταλάντωσης:

$$\sum \vec{F}_y = 0 \Rightarrow F_{\epsilon\lambda'} - W_1 = 0 \Rightarrow K \cdot \Delta\ell_0 = m_1 \cdot g \Rightarrow \boxed{\Delta\ell_0 = \frac{1}{10} = 0,1 \text{ m}}$$

$$\text{άρα } A = \Delta\ell_0 + \Delta\ell \Rightarrow \boxed{A = 0,2 \text{ m}}$$

την $t=0: x = +A \dots \quad \boxed{\varphi_0 = \frac{\pi}{2} \text{ rad}}$

- $\omega = \sqrt{\frac{K}{m_1}} \Rightarrow \omega = \sqrt{\frac{10}{0,1}} \Rightarrow \omega = 10 \text{ rad/s}$

- $\boxed{x = 0,2 \cdot \eta\mu\left(10t + \frac{\pi}{2}\right)} \text{ S.I.}$

Σε τυχαία θέση ισχύει:

$$\frac{K}{E_{\text{ταλ}}} = \frac{3}{4} \Rightarrow K = \frac{3}{4} E_{\text{ταλ}}, \text{ από ΑΔΕΤ: } E_{\text{ταλ,αρχ}} = E_{\text{ταλ,τελ}} \Rightarrow E_{\text{ταλ}} = K + U_{\text{ταλ}} \Rightarrow$$

$$\Rightarrow E_{\text{ταλ}} = \frac{3}{4} E_{\text{ταλ}} + U_{\text{ταλ}} \Rightarrow \frac{1}{4} E_{\text{ταλ}} = U_{\text{ταλ}} \Rightarrow \frac{1}{4} \cdot \frac{1}{2} K A^2 = \frac{1}{2} K \cdot x^2 \Rightarrow x = \pm \frac{A}{2} \text{ άρα } |x| = \frac{A}{2} \quad (1)$$

- η επιτάχυνση: $\alpha = -\omega^2 \cdot x \text{ άρα } |\alpha| = \omega^2 \cdot \frac{A}{2} \Rightarrow |\alpha| = 100 \cdot \frac{0,2}{2} \Rightarrow \boxed{|\alpha| = 10 \frac{\text{m}}{\text{s}^2}}$

Δ3.

$$\text{Η } E_{\text{επ}} = B \cdot u \cdot \ell \rightarrow I_{\text{επ}} = \frac{B u \ell}{R_{\text{ΟΛ}}} \Rightarrow I_{\text{επ}} = \frac{1 \cdot u \cdot 1}{2} \Rightarrow I_{\text{επ}} = \frac{u}{2} \quad (1)$$

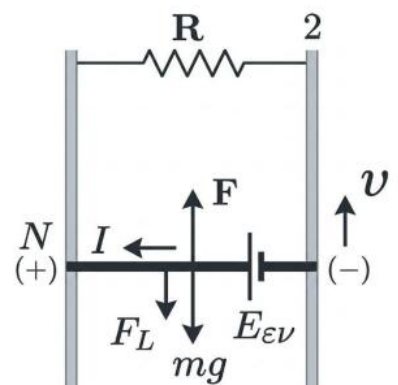
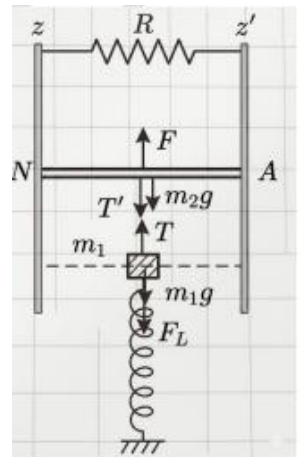
- $\Sigma \vec{F} \uparrow \uparrow \vec{\alpha}$: επιταχύνεται

- $\Sigma \vec{F}_y = m \cdot \vec{\alpha} \Rightarrow F - F_L - W_1 = m \cdot \alpha \Rightarrow \alpha = \frac{3-1-B \cdot I_{\text{επ}} \cdot \ell}{0,1} \Rightarrow$

$$\Rightarrow \alpha = \frac{2-0,5 \cdot u}{0,1} \Rightarrow \boxed{\alpha = 20-5 \cdot u} \text{ αφού } u \uparrow \text{ τότε } \alpha \downarrow \text{ άρα επιταχύνεται}$$

με φθίνοντα ρυθμό

- αν $\alpha = 0$ τότε $u = u_{\text{op}} : 5 \cdot u_{\text{op}} = 20 \Rightarrow \boxed{u_{\text{op}} = 4 \frac{\text{m}}{\text{s}}}$



Δ4.

- Στο χρονικό διάστημα $\Delta t = 0,125\text{s}$ έχει μετατοπιστεί κατά $\Delta x = u_{op} \cdot \Delta t \Rightarrow \Rightarrow \Delta x = 4 \cdot 0,125 \Rightarrow \boxed{\Delta x = 0,5\text{m}}$
- $E_{επ} = B \cdot u_{op} \cdot \ell \Rightarrow E_{επ} = 4\text{Volt}$ άρα $I_{επ} = \frac{E_{επ}}{R_{ΟΛ}} \Rightarrow I_{επ} = \frac{4}{2} = 2\text{A}$
- $Q_{(R)} = I_{επ}^2 \cdot R_{ολ} \cdot \Delta t \Rightarrow Q_{(R)} = 2^2 \cdot 2 \cdot 0,125 \Rightarrow \boxed{Q_{(R)} = 1\text{J}}$ ή $|W_{\vec{f}_L}| = F_L \cdot \Delta x = \dots$
- $W_F = F \cdot \Delta x \Rightarrow W_F = 3 \cdot 0,5 \Rightarrow \boxed{W_F = 1,5\text{J}}$
- $\Pi = \frac{Q_{(R)}}{W_F} \cdot 100 \Rightarrow \Pi = \frac{1}{1,5} \cdot 100 \Rightarrow \Pi = \frac{10}{15} \cdot 100 = \frac{2}{3} \cdot 100 = \boxed{\frac{200}{3}\%}$

